

Slope-deflection method

Slope-deflection equation

$$M_{nf} = \frac{2EI}{L} (2\theta_n + \theta_f - 3\psi) + FEM_{nf}$$

Modified slope-deflection equation

$$M_{rh} = \frac{3EI}{L} (\theta_r - \psi) + \left(FEM_{rh} - \frac{FEM_{hr}}{2} \right)$$

Sidesway degrees of freedom of a frame

$$ss = 2j - [2(f + h) + r + m]$$

Moment Distribution Method

Hinged at the near end and fixed at the far end

$$M = \left(\frac{4EI}{L} \right) \theta$$

$$\bar{K} = \frac{4EI}{L}$$

$$K = \frac{\bar{K}}{4E} = \frac{I}{L}$$

The far end hinged

$$M = \left(\frac{3EI}{L} \right) \theta$$

$$\bar{K} = \frac{3EI}{L}$$

Carryover factor

$$M_{BA} = \begin{cases} \frac{M}{2} & \text{if far end of member is fixed} \\ 0 & \text{if far end of member is hinged} \end{cases}$$

Distribution factor

$$DF = \frac{K}{\sum K}$$

Frames with sidesway

$$M = M_O + M_R = M_O + \left(\frac{R}{Q} \right) M_Q$$

Matrix Structural Analysis

$$\begin{aligned}
 \mathbf{P} - \mathbf{P}_f &= \mathbf{S}d \\
 \mathbf{Q} &= \mathbf{k}\mathbf{u} + \mathbf{Q}_f \\
 \mathbf{Q} &= \mathbf{T}\mathbf{F} \\
 \mathbf{u} &= \mathbf{T}\mathbf{v} \\
 \mathbf{F} &= \mathbf{T}^T\mathbf{Q} \\
 \mathbf{v} &= \mathbf{T}^T\mathbf{u} \\
 \mathbf{F} &= \mathbf{K}\mathbf{v} + \mathbf{F}_f
 \end{aligned}$$

Frame

$$\mathbf{k} = \frac{EI}{L^3} \begin{bmatrix} \frac{AL^2}{I} & 0 & 0 & -\frac{AL^2}{I} & 0 & 0 \\ 0 & 12 & 6L & 0 & -12 & 6L \\ 0 & 6L & 4L^2 & 0 & -6L & 2L^2 \\ \frac{AL^2}{I} & 0 & 0 & \frac{AL^2}{I} & 0 & 0 \\ 0 & -12 & -6L & 0 & 12 & -6L \\ 0 & 6L & 2L^2 & 0 & -6L & 4L^2 \end{bmatrix}$$

$$\mathbf{T} = \begin{bmatrix} \cos \theta & \sin \theta & 0 & 0 & 0 & 0 \\ -\sin \theta & \cos \theta & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & \cos \theta & \sin \theta & 0 \\ 0 & 0 & 0 & -\sin \theta & \cos \theta & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

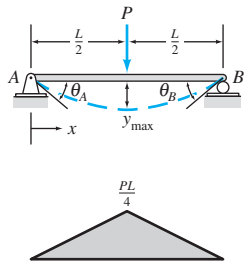
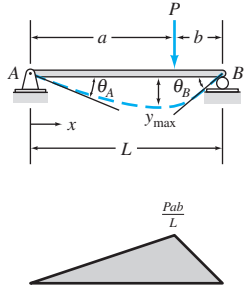
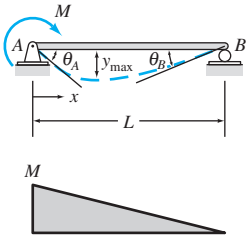
Beam

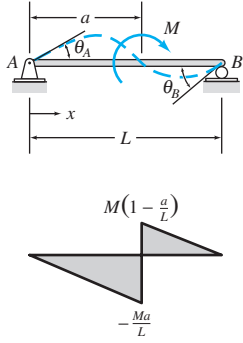
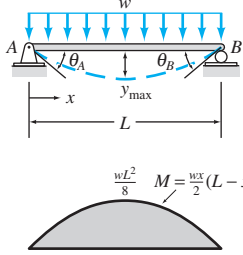
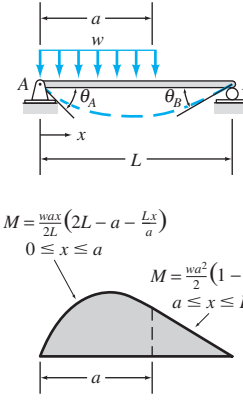
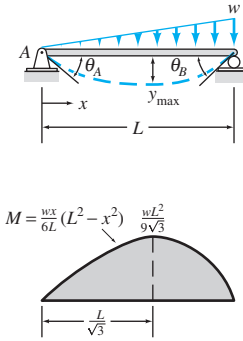
$$\mathbf{k} = \frac{EI}{L^3} \begin{bmatrix} 12 & 6L & -12 & 6L \\ 6L & 4L^2 & -6L & 2L^2 \\ -12 & -6L & 12 & -6L \\ 6L & 2L^2 & -6L & 4L^2 \end{bmatrix}$$

Truss

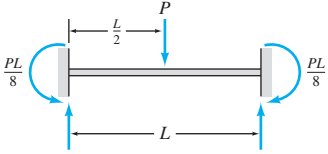
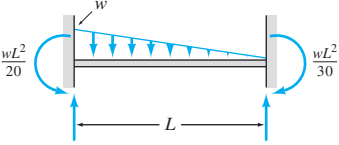
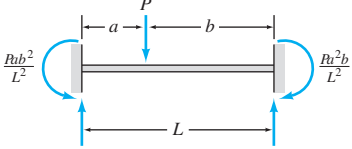
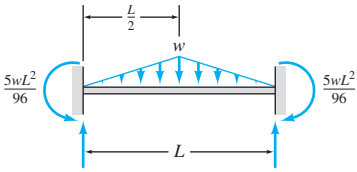
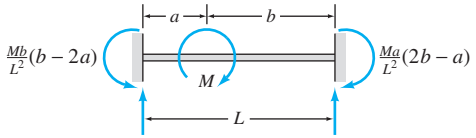
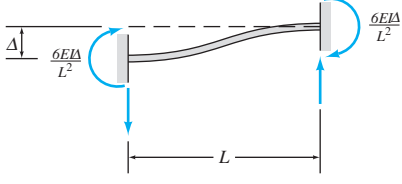
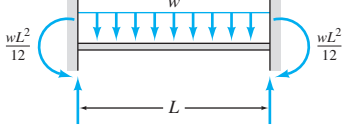
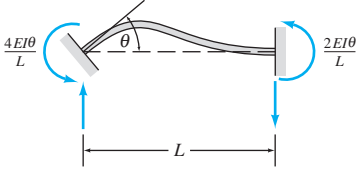
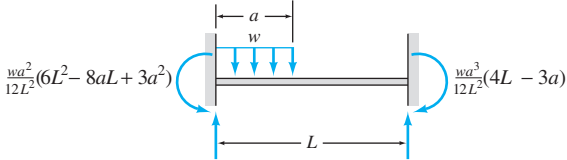
$$\mathbf{k} = \frac{EA}{L} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}$$

$$\mathbf{T} = \begin{bmatrix} \cos \theta & \sin \theta & 0 & 0 \\ 0 & 0 & \cos \theta & \sin \theta \end{bmatrix}$$

Beam, Loading, and Bending Moment Diagram	Equations for Slope and Deflection
	$0 \leq x \leq \frac{L}{2} :$ $\theta = \frac{P}{16EI} (4x^2 - L^2)$ $y = \frac{P}{48EI} (4x^3 - 3L^2x)$ $\theta_A = -\frac{PL^2}{16EI}; \quad \theta_B = \frac{PL^2}{16EI}$ $y_{\max} = -\frac{PL^3}{48EI}$
	$0 \leq x \leq a :$ $\theta = \frac{Pb}{6EIL} (3x^2 + b^2 - L^2)$ $y = \frac{Pb}{6EIL} (x^3 + b^2x - L^2x)$ $a \leq x \leq L :$ $\theta = \frac{Pa}{6EIL} [L^2 - a^2 - 3(L-x)^2]$ $y = \frac{Pa(L-x)}{6EIL} (x^2 + a^2 - 2Lx)$ $\theta_A = -\frac{Pb}{6EIL} (L^2 - b^2)$ $\theta_B = \frac{Pa}{6EIL} (L^2 - a^2)$ For $a \geq b :$ $y_{\max} = -\frac{Pb}{9\sqrt{3}EI} (L^2 - b^2)^{3/2}$ $\text{at } x = \left(\frac{L^2 - b^2}{3} \right)^{1/2}$
	$\theta = -\frac{M}{6EIL} (3x^2 - 6Lx + 2L^2)$ $y = -\frac{M}{6EIL} (x^3 - 3Lx^2 + 2L^2x)$ $\theta_A = -\frac{ML}{3EI}; \quad \theta_B = \frac{ML}{6EI}$ $y_{\max} = -\frac{ML^2}{9\sqrt{3}EI}$ $\text{at } x = L \left(1 - \frac{1}{\sqrt{3}} \right)$

Beam, Loading, and Bending Moment Diagram	Equations for Slope and Deflection
	$0 \leq x \leq a :$ $\theta = \frac{M}{6EI L} (-3x^2 + 6aL - 3a^2 - 2L^2)$ $y = \frac{M}{6EI L} (-x^3 + 6aLx - 3a^2x - 2L^2x)$ $\theta_A = \frac{M}{6EI L} (6aL - 3a^2 - 2L^2)$ $\theta_B = \frac{M}{6EI L} (L^2 - 3a^2)$
	$\theta = -\frac{w}{24EI} (4x^3 - 6Lx^2 + L^3)$ $y = -\frac{w}{24EI} (x^4 - 2Lx^3 + L^3x)$ $\theta_A = -\frac{wL^3}{24EI}$ $\theta_B = \frac{wL^3}{24EI}$ $y_{\max} = -\frac{5wL^4}{384EI} \text{ at } x = \frac{L}{2}$
	$0 \leq x \leq a :$ $\theta = -\frac{w}{24EI L} [4Lx^3 - 6a(2L - a)x^2 + a^2(2L - a)^2]$ $y = -\frac{w}{24EI L} [Lx^4 - 2a(2L - a)x^3 + a^2(2L - a)^2x]$ $a \leq x \leq L :$ $\theta = -\frac{wa^2}{24EI L} (6x^2 - 12Lx + a^2 + 4L^2)$ $y = -\frac{wa^2}{24EI L} (L - x)(-2x^2 + 4Lx - a^2)$ $\theta_A = -\frac{wa^2}{24EI L} (2L - a)^2$ $\theta_B = \frac{wa^2}{24EI L} (2L^2 - a^2)$
	$\theta = -\frac{w}{360EI L} (15x^4 - 30L^2x^2 + 7L^4)$ $y = -\frac{w}{360EI L} (3x^5 - 10L^2x^3 + 7L^4x)$ $\theta_A = -\frac{7wL^3}{360EI}$ $\theta_B = \frac{wL^3}{45EI}$ $y_{\max} = -0.00652 \frac{wL^4}{EI} \text{ at } x = 0.5193L$

FIXED-END MOMENTS

 <p style="text-align: center;">$\frac{PL}{8}$ $\frac{PL}{8}$</p>	 <p style="text-align: center;">$\frac{wL^2}{20}$ $\frac{wL^2}{30}$</p>
 <p style="text-align: center;">$\frac{Pb^2}{L^2}$ $\frac{Pa^2}{L^2}$</p>	 <p style="text-align: center;">$\frac{5wL^2}{96}$ $\frac{5wL^2}{96}$</p>
 <p style="text-align: center;">$\frac{Mb(b-2a)}{L^2}$ $\frac{Ma(2b-a)}{L^2}$</p>	 <p style="text-align: center;">$\frac{6EI\Delta}{L^2}$ $\frac{6EI\Delta}{L^2}$</p>
 <p style="text-align: center;">$\frac{wL^2}{12}$ $\frac{wL^2}{12}$</p>	 <p style="text-align: center;">$\frac{4EI\theta}{L}$ $\frac{2EI\theta}{L}$</p>
 <p style="text-align: center;">$\frac{wa^2(6L^2-8aL+3a^2)}{12L^2}$ $\frac{wa^3(4L-3a)}{12L^2}$</p>	